TELEDYNE | Teledyne FLIR Machine Vision



SPHERICAL VISION SYSTEMS

Ladybug6

Ladybug6 is the leading high-resolution camera that captures 360-degree spherical images on a moving platform in outdoor all-weather conditions. Its industrial grade design and out-of-the-box factory calibration produces 72 Megapixel (MP) images with pixel values that are spatially-accurate within +/- 2 mm at 10-meter distance.

As the newest member of the field-proven Ladybug family, Ladybug6 builds on its machine vision heritage with increased image resolution, enhanced on-board processing, and robust IP67-rated connectors. Support for additional Global Navigation Satellite Systems and advanced APIs, combined with hardware inputs, enable precise camera settings and trigger control. Customer applications include panoramic street image production, road surveying, asset inspection, feature extraction for HD map generation among several others.

FEATURES

HIGHEST ACCURACY AND IMAGE QUALITY

Industry leading calibration combined with global shutter CMOS sensors and high-end optics deliver an unbeatable survey grade spatial accuracy of +/- 2 mm at 10-meters. Additionally, the Ladybug6 captures outstanding images across a wide range of lighting conditions with excellent color response, low noise, and a high dynamic range.

ONBOARD PROCESSING AND FEATURE RICH SDK

Building on our field proven Ladybug5+, the Ladybug6 captures, compresses, and transmits 8-bit or 12-bit pixel data with on-board image processing for optimized workflows. Our feature rich Ladybug Software Development Kit (SDK) enables image acquisition, spherical and panoramic image production, and fine grain control of pre & post acquisition camera settings via a user friendly and friendly user interface.

BUILT FOR THE OUTDOORS

Designed from the ground up to capture images from moving platforms in outdoor environments, the Ladybug6 features an IP67 rating, industrial grade IP67 rated connectors, a wide operating temperature range (-30° C to 50° C), support for additional Global Navigation Satellite Systems, and trigger control by hardware or software with advanced APIs for complete camera control.

APPLICATIONS

HD Mapping

- Asset Management
- **Roadside Inspection**
- Street View
- Road Maintenance
- Heritage Scanning
- **Building Management**

| SPECS | LD6-U3-122S7C |
|----------------------------------|--|
| Full Resolution | 12,288 x 6,144 (72 MP) |
| Frame Rate | 15 FPS JPEG at 72 MP resolution / 29.9 FPS JPEG at 36 MP resolution |
| Interface | M12 X-coded 8-pin USB 3.1 Gen 1 for camera control and video data |
| General Purpose I/O Ports | 12-pin GPIO connector for external trigger input, strobe output, power, and PPS |
| Dimensions/Mass | 198 mm (height) x 269 mm (diameter) / 5.2 kg |
| Optics | Six high quality 6.94 mm focal length lenses |
| Case | Machined aluminum housing, anodized red or black |
| Protection | IP67 |
| Mounting | Five M4-0.7 x 8 mm mounting holes to attach to tripod adapter or custom mount |
| Desiccant | Desiccant plug to minimize moisture in the enclosure and prevent lens fogging |
| Fransfer Rates | 5 Gbit/s |
| Power Interface | via GPIO only, not USB3 interface |
| ower | 12-24 V via GPIO (external power required) / 13 W maximum |
| nvironmental Sensors | Temperature, Humidity |
| .ED | One general purpose status LED for monitoring camera power, initialization, and USB3 activity |
| ield of View | ~90% of full sphere |
| Angular FOV (per rotated sensor) | Vertical: ~117.4° / Horizontal: ~85.9° |
| Spherical Distance | Calibrated from 2 m to infinity |
| ocus Distance | ~200 cm. Objects have an acceptable sharpness from ~100 cm to infinity |
| ligh Dynamic Range | Cycle 4 gain and exposure presets |
| External Trigger Modes | Standard, bulb, skip frames, overlapped, and multi shot trigger modes |
| Image Processing | Luminance: Black Level, Exposure Tonal: Gamma, Tone Mapping Color: White Balance, Saturation, Leveling, Noise Reduction, Sharpening, False color removal |
| Gain | 0 - 18 dB |
| Gamma | 0.50 to 4.00 |
| mage Output (SDK) | Image Projections: Panoramic, Dome, Cubic, Individual Sensor, Rectified File Types: JPG, BMP, PNG, TIFF |
| Video Output (SDK) | Video .AVI: H.264 Video .MP4: H.264, HEVC/H.265, AV1 |
| Shutter Speed | 0.02 ms to 2 seconds (extended shutter) |
| Shutter Type | Global shutter |
| Memory Channels | 2 memory channels for custom camera settings |
| Flash Memory | 1 MB |
| Recommended RAM | 8 GB for capture and recording / 16 GB for post processing |
| Recommended Operating System | Windows 10 64-bit or Ubuntu 20.04 64-bit for capture, recording, and post processing / ARM64 for capture only |
| Recommended CPU | 11th Gen Intel [®] Core™ i7 processor |
| Recommended Compilers | Microsoft Visual Studio 2015 or newer / g++ 9.3.0 or newer |
| Machine Vision Standard | IIDC v1.32 |
| Compliance | CE, RCM, FCC, RoHS, KCC |
| Temperature | Operating: -30° to 50°C Storage: -30° to 60°C |
| Humidity | Operating: 20 to 80% (no condensation) |

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